

## A comparative study of MHD flow Analysis in a Porous Medium by Using Differential Transformation Method and Variational Iteration Method

K.Jabeen, M.Mushtaq, R.M.Akram

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**Abstract.** The purpose of the current study is to examine Magnetohydrodynamic (MHD) boundary layer flow having magnetic characteristics and behavior of electrically transmitted viscous incompressible fluids over a stretching sheet fixed in a porous medium. This porosity on the flow field is typically analyzed under the effects of magnetic field (MF) and permeability. The results for various Prandtl numbers on temperature profile has also been observed. By using Darcy Model in order to a variable MF, we have considered the flow of a viscous fluid through porous media. The series solution of the non-linear boundary layer problem of flow field is obtained by using DTM as well as by VIM along with Pade approximant (PA). For solving BVPs the combination of DTM-Pade and VIM-Pade approximation is shown to be a powerful techniques. The methods are effective and convenient subject to the comparison of the obtained results and with already available results shown in the literature. It is observed that both magnetic field and the permeability parameter of porous medium impart to thinning of the boundary layer. Same in the case of thermal effects, temperature profile decreases with the increment of Prandtl number.

**Key Words and Phrases:** Magnetohydrodynamics, DTM, VIM, Pade-approximation, Porous Medium, Magnetic field.

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### 1. Introduction

The aim of the current work is to investigate porous medium for steady-state incompressible viscous flow of an electrically conducting fluids under the influence of  $MF$ . For this purpose, to overcome the difficulties concerning the closed form solution in non linear boundary value problem we have used semi-analytical methods name as Differential transformation method and Variational iteration method with the combination of PA [1]. Although there exists many other research studies with great interest have largely been used such as Perturbation techniques, Homotopy Perturbation method (HPM), Homotopy Analysis methods (HAM), Adomian Decomposition method (ADM) and Successive approximation method. But this work mainly focuses on the behavior of DTM, VIM and PA [2, 3]. For the solution of linear and non linear Differential equations (NLDE) these methods are strongly effective and reliable which can be directly applied

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to NLDE in physics, engineering and mathematics. They do not require any linearization and perturbation. Although these methods has some drawbacks , they are applicable in the small region but invalid in an unbound domain. To overcome this issue we have consider PÅ . By using the above mentioned methods we obtain the solution in the form of series, the series may diverge when the variable involved in the problem approaches to infinity. For the settlement of this situation a combination of PÅ [2] has been used to get approximate solutions.

In the manifestation of a MF the flow of an electrically conducting fluids having much momentousness in multiple disciplines of technology and engineering such as MHD pumps, MHD power generation and MHD flow meter etc. In many extents of engineering and industrial areas of interest the porous media flow plays a significant role [3]. Moreover, in polymer industries wide applications are to be found in particular flow on a stretching sheet. A little while back, Mohammadreza et.al. and Peker et. al. have studied viscous fluid flows on a stretching sheet with a constant rate of stretching and the fluid flow in order to a variable MF. In their work, they did not consider the porous media. Later, a stretching sheet with uniform matrix subjected to a MF strength fixed in a porous medium propotional to  $x^{(n-1)/2}$  and non linear stretching sheet  $x^n$  had been discussed [4]. Many authors used to consider the strength of MF as constant. In the current work we have focused on the following two main objectives; the first one is the study of wedge flow through porous media subjected to a MF leads towards a modified model of Falkner-skam equation while the second purpose is to investigavte the stability of the *DTM* and *VIM* empowered with PÅ [10, 12]. The following are the Prandtl Boundary layer (B.1) Darcian flow equations, [1]

$$u_x + v_y = 0 \quad (1)$$

$$uu_x + vv_y = \nu u_{xx} - \sigma \frac{D^2(x)u}{\rho} - \frac{uv}{kp(x)} \quad (2)$$

$$uT_x + vT_y = \alpha T_{yy} \quad (3)$$

variable magnetic field  $D(x)$  and  $kp(x)$  variable Porosity are as follows,

$$D(x) = D_0(x)x^{\frac{n-1}{2}}, \quad kp(x) = kp'x^{1-n}$$

subject to the boundary conditions (BCs),

$$\begin{cases} y = 0, \\ u = cx^n, v = 0, T = T_w, \\ y \rightarrow \infty, \\ u \rightarrow 0, T \rightarrow T(\infty), \end{cases}$$

Where  $c$  is stretching rate. The continuity equation is satisfied by choosing  $\psi(x, y)$  as a stream function which is,

$$u = \psi_y$$

and  $v = -\psi_x$

Introducing similarity transformation,

$$\begin{cases} \eta(x, y) = x^{\frac{n-1}{2}} y \sqrt{\frac{c(n+1)}{2\nu}}, \\ \psi(x, y) = x^{\frac{n+1}{2}} f(\eta) \sqrt{\frac{2c\nu}{(n+1)}} \end{cases}$$

$$u = cx^n f' \quad (4)$$

$$v = -\sqrt{\frac{c\nu(n+1)}{2}} x^{\frac{n-1}{2}} [f + (\frac{n-1}{n+1})\eta f'] \quad (5)$$

so the transformed ODEs along their boundary conditions are

$$f''' - (M + \frac{1}{kp})f' + f f'' - \beta f'^2 = 0 \quad (6)$$

$$\frac{1}{Pr}\theta'' + \theta' f = 0, \quad (7)$$

$$\left\{ f(0) = 0, f'(0) = 1, f''(0) = 2\alpha(\text{say}), f'(\infty) = 0, \theta(0) = 1, \theta(\infty) = 0, \theta'(0) = A(\text{say}), \right.$$

$$M = \frac{2\sigma D_0^2(x)}{\rho c(n+1)}, \text{ and } \frac{1}{kp} = \frac{2\nu}{c(n+1)kp'},$$

where M stands for the magnetic parameter,  $kp$  stands for permeability parameter,  $\beta$  is power index,

$\alpha$  and  $A$  are unknowns to be determined.

### 1.1. Differential Transformation Method

Differential transformation method (DTM) was purposed by Zhou. The method was developed to tackle initial value problems (IVP) in electric circuit theory. DTM is based on Taylor series expansion. In this method we have applied some transformation rules. The set of fundamental equations are reduced to Ordinary Differential equations (ODEs), then these equations along with boundary conditions are transformed under the rules described by DTM to yields the desired solution of the problem. Basic definitions and operations of DTM are introduced for the function  $f(\eta)$  as given below, [13]

$$F(r) = \frac{1}{r!} \frac{d^r}{d\eta^r} f(\eta), \quad (8)$$

Where basic original function is  $f(\eta)$  while transformed function is  $F(r)$  known as Spectrum of  $f(\eta)$  at  $\eta = \eta_0$  in the  $r^{th}$  domain. Also the inverse of  $F(r)$  is given as,

$$f(\eta) = \sum_{r=0}^{\infty} F(r)(\eta - \eta_0)^r, \quad (9)$$

On formulation of equation (10) and (11)  $f(\eta)$  is,

$$f(\eta) = \sum_{r=0}^{\infty} \left[ \frac{d^r}{d\eta^r} f(\eta) \right]_{(\eta=\eta_0)} \frac{(\eta - \eta_0)^r}{r!}, \quad (10)$$

Although the method is based on Taylor series expansion but it does not symbolically calculate the derivatives. So, the desired derivatives are obtained by an iterative method,

In fact,  $f(\eta)$  in equation (9) is expressed by a finite series which can be formulated as,

$$f(\eta) = \sum_{r=0}^N F(r)(\eta - \eta_0)^r, \quad (11)$$

where  $N$  is a series size. here we have considered the differential transformed function (DTF) about the point  $\eta = 0$  in table-1 and it is assumed that  $\eta_0 = 0$  in this section.

## 1.2. Variational Iteration Method (VIM)

The VIM was proposed by Ji-Huan-He which is a modified general Lagrange multiplier used to handle a variety of homogeneous, inhomogeneous, linear and non-linear problems with approximations which rapidly converges to exact solution. This method tackle both linear and nonlinear problems with same manners and this method is free from any specification, linearization and perturbation such as ADM, HPM and HAM. The VIM gives the series solution that converges to closed form solution if an analytical solution exists. If the analytical solution does not exist then the computed series is used for numerical purposes. [3, 4] The main steps of the methods are as follows: consider the non-linear equation

$$L_1 g + M_1 g = y(t) \quad (12)$$

Where  $L_1$  is linear and  $M_1$  is non-linear operators and  $y(t)$  represents the inhomogeneous term. The correction functional of above equation is

$$g_{n+1}(x) = g_n(x) + \int_0^x \lambda(t) (L_1 g_n(t) + M_1 g_n(t) - y(t)) dt \quad (13)$$

Where  $\lambda$  is a Lagrange-multiplier and it may be constant or a function and  $g_n$  is a restricted to behave as a constant. The initial guess can be taken as follows

$$\begin{cases} g_0(x) = g(0), \text{ for } g'_n \\ g_0(x) = g(0) + xg'(0), \text{ for } g''_n \\ g_0(x) = g(0) + xg'(0) + \frac{1}{2!}x^2g''(0), \text{ for } g'''_n \\ \dots \\ \dots \end{cases}$$

the compact form of the solution is

$$g(x) = \lim_{n \rightarrow \infty} g_n(x) \quad (14)$$

### 1.3. Pade-Approximation

Suppose a power series  $\sum_{r=0}^{\infty} \hat{a}_r t^r$  representing a function  $f(\eta)$ , this implies,

$$f(\eta) = \sum_{r=0}^{\infty} \hat{a}_r t^r, \quad (15)$$

Basically, Pade is a rational function and the notation for such Pade is,

$$[I, J] = \frac{S_I(t)}{Q_J(t)}, \quad (16)$$

where  $S_I(t)$  is a polynomial of degree at most  $I$  and  $Q_J(t)$  is a polynomial of degree at most  $J$ , we have,

$$f(\eta) = \hat{a}_0 + \hat{a}_1 t + \hat{a}_2 t^2 + \hat{a}_3 t^3 + \hat{a}_4 t^4 + \dots, \quad (17)$$

$$S_I(t) = \hat{s}_0 + \hat{s}_1 t + \hat{s}_2 t^2 + \hat{s}_3 t^3 + \hat{s}_4 t^4 + \dots + \hat{s}_I(t)^I, \quad (18)$$

$$Q_J(t) = \hat{q}_0 + \hat{q}_1 t + \hat{q}_2 t^2 + \hat{q}_3 t^3 + \hat{q}_4 t^4 + \dots + \hat{q}_J(t)^J, \quad (19)$$

equation (16) reveals that  $I + 1$  numerator coefficients and  $J + 1$  denominator coefficients are there. since we can clearly multiply numerator and denominator by a constant and  $[I, J]$  remains unvaried Now imposing the normalized conditions,[8, 9]

$$Q_J(0) = 1 = \hat{q}_0 \quad (20)$$

so, there are  $I + 1$  independent numerator coefficients and  $J$  independent denominator coefficients making  $I + J + 1$  unknown coefficients. This number gives  $[I, J]$  ought to fit

the power series with the orders,

$$1, t, t^2, t^3, t^4, \dots, t^{I+J},$$

The formal power series is,

$$\sum_{r=0}^{\infty} \hat{a}_r t^r = \frac{\hat{s}_0 + \hat{s}_1 t + \hat{s}_2 t^2 + \hat{s}_3 t^3 + \hat{s}_4 t^4 + \dots + \hat{s}_I(t)^I}{\hat{q}_0 + \hat{q}_1 t + \hat{q}_2 t^2 + \hat{q}_3 t^3 + \hat{q}_4 t^4 + \dots + \hat{q}_J(t)^J} + O(t^{I+J+1}), \quad (21)$$

by cross multiplication and comparing we will get the following set of equations,

$$\left\{ \begin{array}{l} \hat{a}_0 = \hat{s}_0, \\ \hat{a}_1 + \hat{a}_0 \hat{q}_1 = \hat{s}_1, \\ \hat{a}_2 + \hat{a}_1 \hat{q}_1 + \hat{a}_0 \hat{q}_2 = \hat{s}_2, \\ \cdot \\ \cdot \\ \hat{a}_I + \hat{a}_{I-1} \hat{q}_1 + \dots + \hat{a}_0 \hat{q}_I = \hat{s}_I \end{array} \right. \quad (22)$$

and

$$\left\{ \begin{array}{l} \hat{a}_{I+1} + \hat{a}_I \hat{q}_1 + \dots + \hat{a}_{I-J+1} \hat{q}_J = 0, \\ \hat{a}_{I+2} + \hat{a}_{I+1} \hat{q}_1 + \dots + \hat{a}_{I-J+2} \hat{q}_J = 0, \\ \cdot \\ \cdot \\ \hat{a}_{I+J} + \hat{a}_{I+J-1} \hat{q}_1 + \dots + \hat{a}_I \hat{q}_J = 0, \end{array} \right. \quad (23)$$

$\hat{a}_n = 0$  for  $n < 0$  and  $\hat{q}_{M_1} = 0$  for  $M_1 > J$ . for non-singular solution of equation (22) and (23) then the direct solution is,

$$[I, J] = \frac{\begin{vmatrix} \hat{a}_{I-j+1} & \hat{a}_{I-j+2} & \cdots & \hat{a}_{I+1} \\ \vdots & \vdots & \ddots & \vdots \\ \hat{a}_I & \hat{a}_{I+1} & \cdots & \hat{a}_{I+J} \end{vmatrix}}{\sum_{M_1=J}^I \hat{a}_{M_1-J} t^I \quad \sum_{M_1=J-1}^I \hat{a}_{M_1-J+1} t^{M_1} \cdots \quad \sum_{M_1=0}^I \hat{a}_{M_1} t^{M_1}} \begin{vmatrix} \hat{a}_{I-j+1} & \hat{a}_{I-j+2} & \cdots & \hat{a}_{I+1} \\ \vdots & \vdots & \ddots & \vdots \\ \hat{a}_{L_1} & \hat{a}_{L_1+1} & \hat{a}_{I+J} & \\ t^J & t^{J-1} & \cdots & 1 \end{vmatrix} \quad (24)$$

In PÀ , every choice of  $I$  and  $J$  (the degree of numerator and denominator respectively) leads to an approximant. In order to find a best approximant we have considered  $I = J$  to avoid any complexity regarding the shape of the solution. We directly apply PÀ about the point  $x = 0$ , by using the symbolic computational software *MAPLE*. It is essential to get the best convergence of the truncated series to employ the PÀ, without using this technique the semi-analytical solution obtained by VIM and DTM can not satisfy the boundary conditions in an infinite domain. Although to get desired accuracy, the higher order approximation procedure is required, [5, 6]

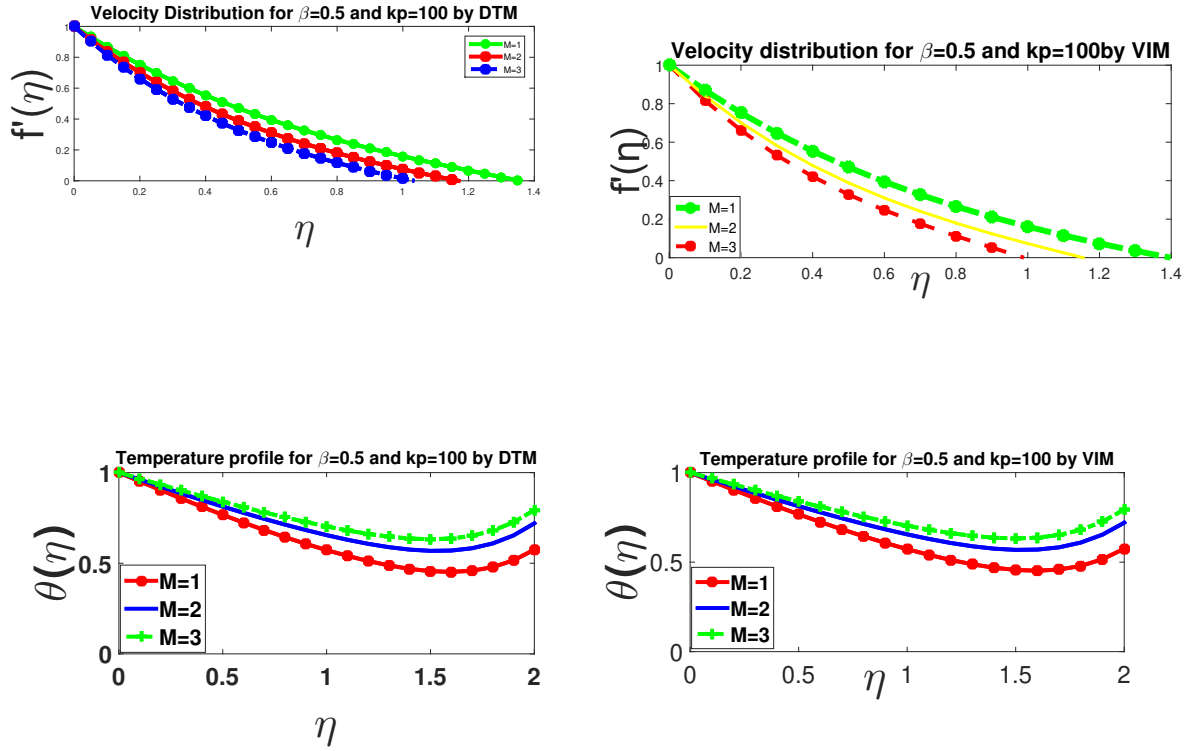


Figure 1: Velocity and Temperature profile for various values of Magnetic parameter M by DTM and VIM

**Table-1: Some fundamental operations of DTM**

Sr.no	Original Function	Transformed Function
1	$s(\eta) = \lambda t(\eta)$	$S(k) = \lambda T(k)$
2	$s(\eta) = \alpha t(\eta) \pm \beta u(\eta)$	$S(k) = \alpha T(k) \pm \beta U(k)$
3	$s(\eta) = \frac{d^r}{d\eta^r} t(\eta)$	$S(k) = \frac{(k+r)!}{k!} T(k+r)$
4	$s(\eta) = t(\eta)u(\eta)$	$S(k) = \sum_{r=0}^k T(r)U(k-r)$
5	$s(\eta) = t(\eta) \frac{d^2}{d\eta^2} u(\eta)$	$\sum_{r=0}^k (k-r+1)(k-r+2)T(r)U(k-r+2)$



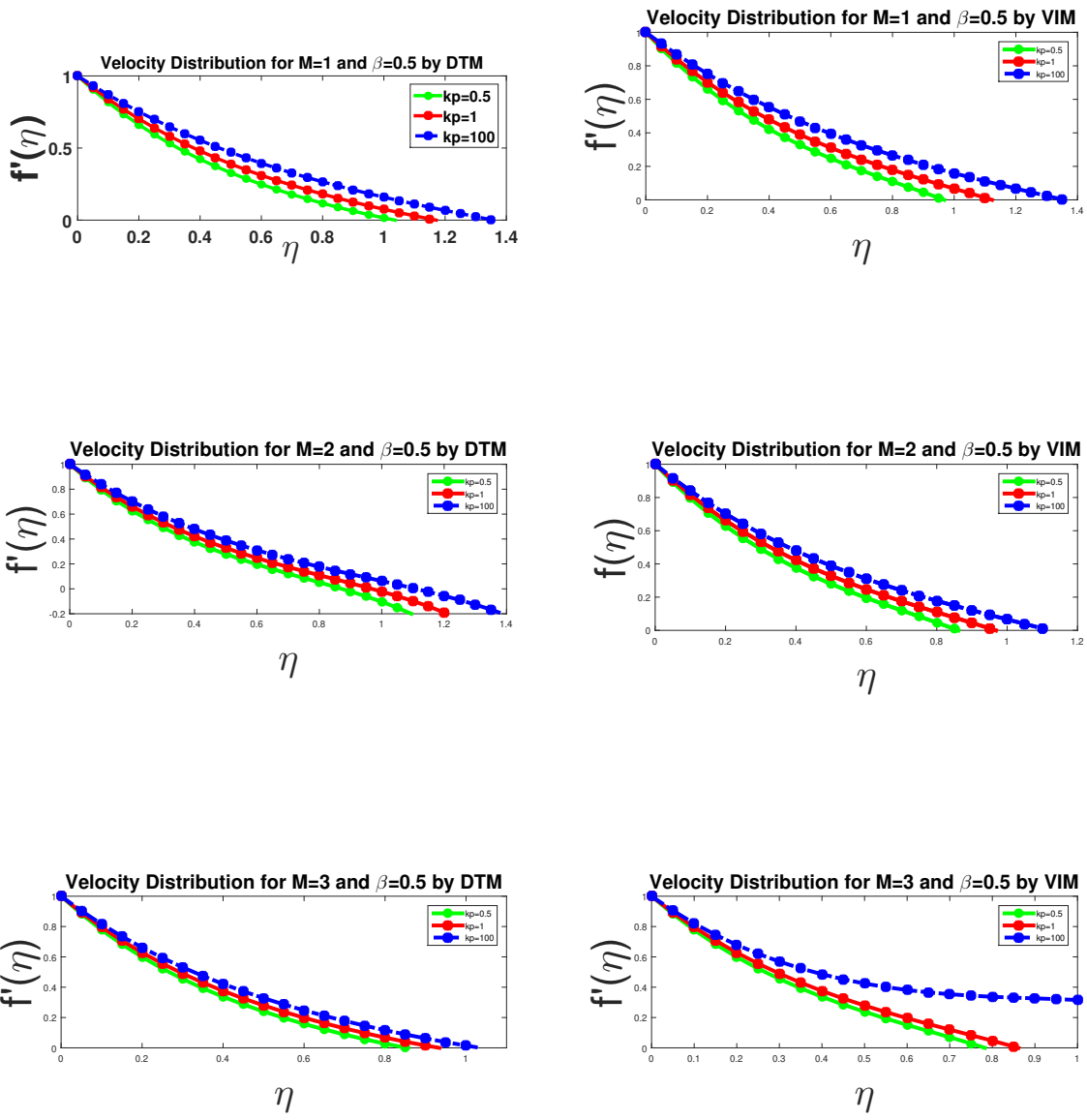


Figure 2: Velocity profile  $k_p=0.5, k_p=1, k_p=100$  by DTM and VIM

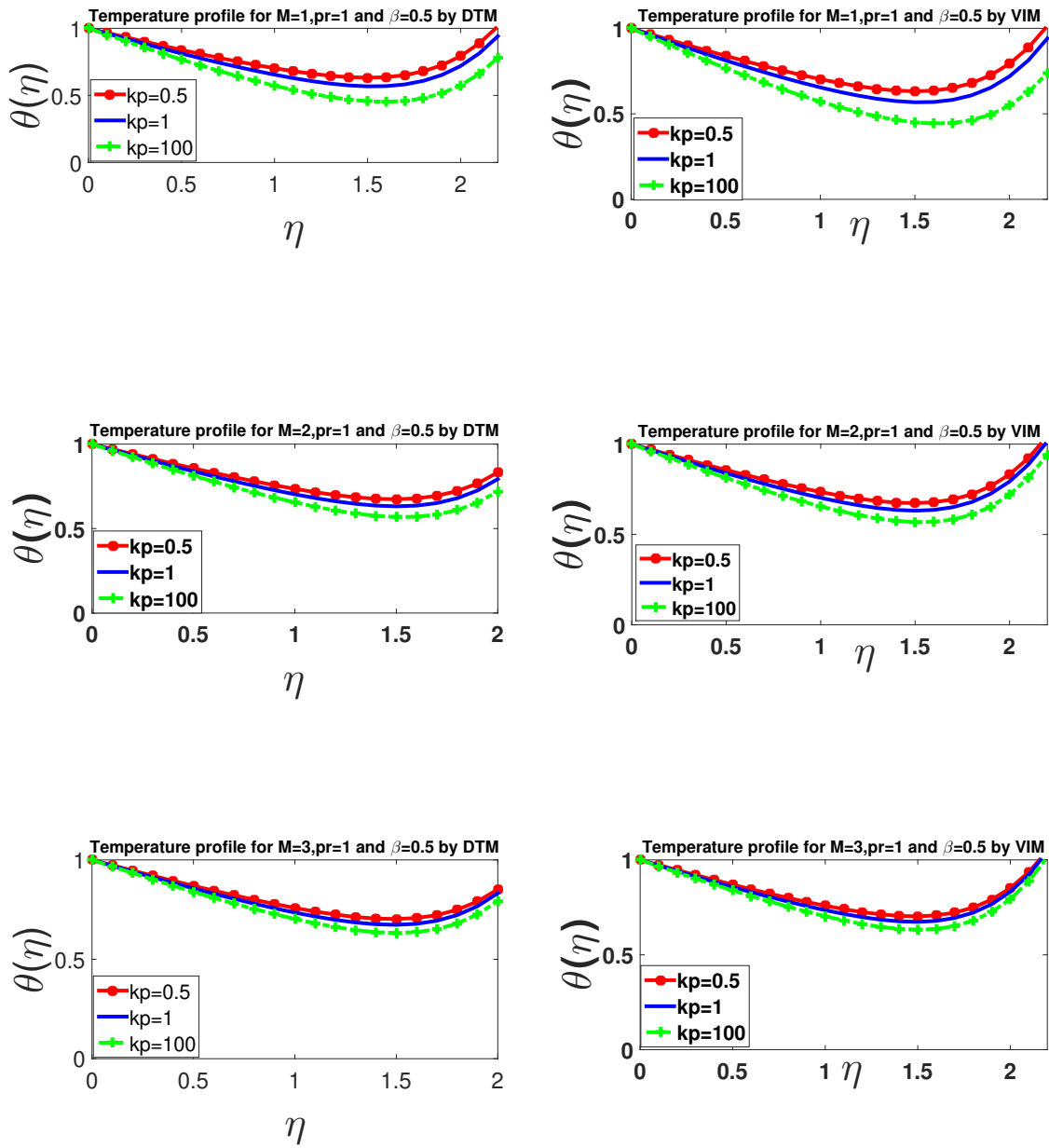


Figure 3: Temperature profile  $kp=0.5, kp=1, kp=100$  by DTM and VIM

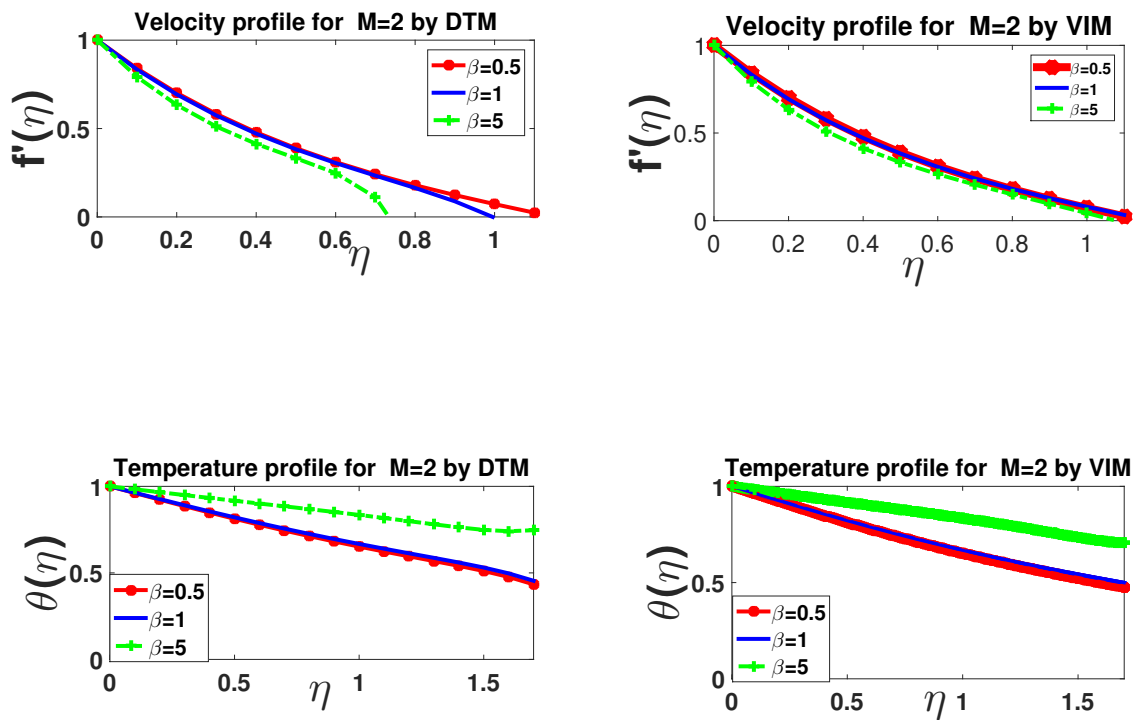


Figure 4: Velocity and Temperature profile for various values of  $\beta$  when  $M=2$  by DTM and VIM

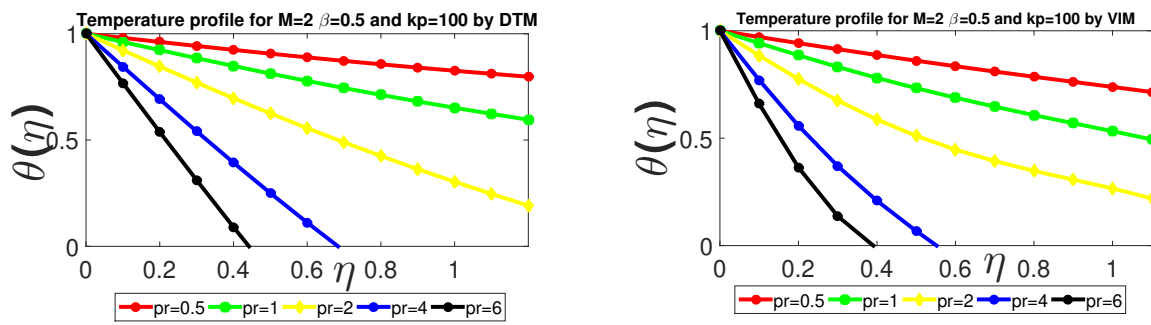


Figure 5: Temperature profile for different prandtl numbers  $M = 2$ ,  $\beta = 0.5$  and  $kp = 100$  by DTM and VIM

**Table-2: Comparison between the numerical results of velocity distribution obtained by DTM and VIM when  $M = kp = \beta = 0.5$**

$\eta$	$f(\eta),DTM$	$f(\eta),VIM$
0.0	0.0000000000	0.0000000000
0.1	0.0911529382	0.0911529382
0.2	0.1663892400	0.1663892427
0.3	0.2280668237	0.2280668491
0.4	0.2781691442	0.2781691674
0.5	0.3183491031	0.3183484809
0.6	0.3499694111	0.3499648276
0.7	0.3741380536	0.3741186098
0.8	0.3917372430	0.3916754343
0.9	0.4034433232	0.4032818451
1.0	0.4097333975	0.4093706527

**Table-3: Numerical analysis of results obtained by DTM and VIM when**

$M = kp = \beta = 0.5$

$\eta$	$f'(\eta),DTM$	$f'(\eta),VIM$	$\theta(\eta),DTM$	$\theta(\eta),VIM$
0.0	1.00000	1.0000000000	1.0000000000	1.0000000000
0.1	0.8276814941	0.8276814963	0.9643221086	0.9643221087
0.2	0.6809667103	0.6809667961	0.9289630514	0.9289630519
0.3	0.5558833678	0.5558837292	0.8941832201	0.8941831843
0.4	0.4489111212	0.4489099215	0.8601839810	0.8601837706
0.5	0.3569532942	0.3569376075	0.8271142983	0.8271135457
0.6	0.2772946240	0.2772191571	0.7950776250	0.7950758469
0.7	0.2075451639	0.2072965134	0.7641377641	0.7641355735
0.8	0.1455646023	0.1449166342	0.734217077	0.7342545255
0.9	0.08935417176	0.08793396542	0.7056161362	0.7056511922
1.0	0.03689496702	0.03419985184	0.6779519531	0.6780950993

**Table-4: Analysis of skin friction coefficient  $f''(0)$  and the rate of heat transfer  $\theta'(0)$  by DTM and VIM**

$\beta$	$M$	$kp$	$f''(0),DTM$	$f''(0),VIM$	$\theta'(0),DTM$	$\theta'(0),VIM$
0.5	1	100	-1.381589474	-1.381589474	-0.7238040090	-0.7238040090
0.5	2	100	-1.720476298	-1.720476298	-0.5812343950	-0.5812343950
0.5	3	100	-2.005888928	-2.005888928	-0.4985320902	-0.4985320902
1	2	100	-1.801186973	-1.801186973	-0.5551894470	-0.5551894470
5	2	100	-2.389820330	-2.389820330	-0.4184414985	-0.4184414985
0.5	3	0.5	-2.479707362	-2.479707362	-0.4032733924	-0.4032733924

## 1.4. Results and Discussion

Under the usual Boundary layer approximations, the boundary layer equations such as continuity equation, momentum equation and energy equation are transformed in to ODEs. This set of nonlinear ODEs along with the boundary conditions are calculated by using semi-analytical techniques *DTM* and *VIM* by systematic guessing of  $f''(0)$  and  $\theta'(0)$  by PÀ until the boundary conditions are satisfied at infinity with the help of computer softwares. Figure (1) by *DTM* and *VIM* depicts that the velocity and temperature profiles for different values of Magnetic parameter. From graphical representation it is observed that in the boundary layer region, the velocity profiles decreases when the magnetic parameter  $M$  increases. This result validates the physical behavior of Magnetic field. But transverse effects are observed on the Temperature profiles for varoius values of Magnetic parameter  $M$ . Clearly using the two methods it can be seen in figures, as the  $M$  increases through 1 to 3 the temperature boundary layer thickness also increases. It is also noticed that graphically both the methods are in well agreement. In figures 2 and 3 when the permeability parameter  $kp$  increases from 0.5 to 100 the velocity profile thickness increases due to more injection or suction of the fluid. But increase in the permeability parameter ( $kp$ ) leads to decrease in fluid temperature profile, which is due the fact the *Darcian* body force transfers heat from solid surface to the fluid layers. The *DTM* and *VIM* shows good agreement that can be seen in velocity profile as well as in temperature profiles. The velocity profile is also calculated for various values of  $\beta$  as shown in figure 4 by applying the two methods under consideration and it is observed that the velocity profile reduces at all points when  $\beta$  varies from 0.5 to 5. These values of  $\beta$  leads to non-linear variation of plate velocity as well as MF strength. While  $\beta = 1$  corresponds the linear variation of velocity as well as constant MF. From this we conclude that, to increase the fluid velocity, variation of plate velocity contributes more than the MF strength. Also it is useful to mention that the temperature profile increases with the increment of the values of  $\beta$ . Effects of Prandtl number on thermal boundary layer can be seen via figure.5 which reveals that fluid with larger prandtl number have a thinner thermal boundary layer, due to more heat transfer between the stretching sheet and viscous fluid. In Table (2) the skin friction coefficient is also computed by *DTM* and *VIM*. It is observed that in the existence of porous media and MF the magnitude of skin friction increases but adverse effects are to be seen due to the power index of MF.

## 1.5. Conclusion

In this paper, *DTM* and *VIM* along with PÀ has been employed to investigate the heat and mass transfer of a steady MHD flow. We have seen that the obtained results are in good agreement with the previous work. The velocity and temperature profiles are obtained by *DTM* and *VIM* along with PÀ. In this work to avoid the complexity, we have considered the diagonal pade  $[2/2]$  that is the about  $\eta^5$ . It is quite obvious as the order increases it will yeild better approximation and produces higher accuracy. It is observed that due to resistive force of electromagnetic which is lorentz force the velocity decreases. Also the velocity profile at all the points reduces under the influence of power

index and increases with the increase in the permeability parameter. Due to magnetic field and permeability the shear stress increases but the power index of magnetic field shows reverse effects. Same as in the case of thermal profile, an increase in magnetic parameter  $M$  will increase the thermal boundary layer but reverse effects are to be seen in the case of permeability parameter ( $kp$ ) Also as expected, by increasing the prandtl number the temperature profile gets thinner.

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K.Jabeen

*Department of Mathematics,University of the Engineering and  
Technology Lahore,Pakistan*

*E-mail: kanwaljabeen44@yahoo.com*

M.Mushtaq

*Department of Mathematics,University of the Engineering and  
Technology Lahore,Pakistan*

R.M.Akram

*Department of Mathematics,University of the Engineering and  
Technology Lahore,Pakistan*

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