

On the existence of a solution to the inverse problem of finding the right side of parabolic equation in a domain with a moving

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Abstract. The paper considers to investigate corrects of the inverse problem for finding the unknown right side, which depends on the time variable. It is considered the Neumann mixed boundary value problem on domain which the boundary depends on the time variable, an additional condition for finding the unknown function is given in the integral form. A theorem on the existence of a generalized solution of the considered inverse problem is proved.

Key Words and Phrases: Parabolic equation, domain with moving boundaries, inverse problem, the existence of a solution.

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1. Introduction and main result

Let $x = \gamma(t)$, $0 < a = \gamma(0) \leq \gamma(t) \leq \gamma(T) = b < \infty$, $0 < T = \text{const}$, $a, b = \text{const}$, $t \in [0, T]$ be the given function, (x, t) be an arbitrary point in the bounded domain $D = (0, \gamma(t) \times (0, T]$. The spaces $C^l(\cdot)$, $C^{l+\alpha}(\cdot)$, $C^{l,l/2}(\cdot)$, $C^{l+\alpha,(1+\alpha)/2}(\cdot)$, $l = 0, 1, 2$, $0 < \alpha < 1$ and the norms in these spaces are defined as in [see 1, 2]:

$$\|p\|_D^{(l)} = \sum_{k=0}^l \sup_D \left| \frac{\partial^k p(x, t)}{\partial x^k} \right|, \quad \|q\|_T^{(l)} = \sum_{k=0}^l \sup_{[0, T]} \left| \frac{\partial^k q(x, t)}{\partial t^k} \right|,$$

$$p_t = \frac{\partial p(x, t)}{\partial t}, \quad p_x = \frac{\partial p(x, t)}{\partial x}, \quad p_{xx} = \frac{\partial^2 p(x, t)}{\partial x^2}, \quad q' = \frac{dq(t)}{dt}.$$

We consider the following inverse problem on determining a pair of functions $\{f(t), u(x, t)\}$:

$$u_t - u_{xx} = f(t)g(x), \quad (x, t) \in D, \quad (1)$$

$$u(x, 0) = \varphi(x), \quad x \in [0, a], \quad (2)$$

$$u_x(0, t) = \psi_0(t), \quad u_x(\gamma(t), t) = \psi_1(t), \quad t \in [0, T], \quad (3)$$

$$\int_0^c u(x, t) dx = h(t), \quad t \in [0, T]. \quad (4)$$

where c is a constant such that $0 < c < a$, $g(x), \varphi(x, t), \psi_0(t), \psi_1(t), h(t), \gamma(t)$ are given functions.

“Direct” problems for parabolic equations in non-cylindrical domains are considered in the works [2,3,4].

The coefficient inverse problem for a parabolic equations in domains with moving boundaries were studied in the papers [5,6].

Problem (1)-(4) belongs to the class of Hadamard ill-posed problems. Therefore, this problem should be treated proceeding from the general concepts of the theory of ill-posed problems.

For A.N.Tikhonov correct problems, the existence of a solution is a priori assumed and justified by the physical meaning of the problem under consideration.

Despite the fact that the proof of the existence of a solution to ill-posed problems requires some additional conditions for the input data, but from the point of view of constructing algorithms for the exact or approximate finding of a solution of the problem, it is certainly of practical interest.

We take the following assumptions for the data of problem (1)-(4):

- 1.1. $g(x) \in C^\alpha([0, b])$, $\int_0^c g(x) dx = g_0 \neq 0$, (without breaking the generality, for the prostate we take $g_0 = 1$)
- 1.2. $\varphi(x) \in C^{2+\alpha}[0, a]$, $\int_0^c \varphi(x) dx = h(0)$;
- 1.3. $\psi_0(t), \psi_1(t) \in C^{1+\alpha}[0, T]$; $\varphi'(0) = \psi_0(0)$; $\varphi'(a) = \psi_1(a)$
- 1.4. $h(t) \in C^{1+\alpha}[0, T]$, $t \in [0, T]$.
- 1.5. $\gamma(t) \in C^{1+\alpha}[0, T]$, $\gamma'(t) > 0$, $t \in [0, T]$, $0 < a = \gamma(0) \leq \gamma(t) \leq \gamma(T) = b < +\infty$.

Definition 1. The a pair of functions $\{f(t), u(x, t)\}$ is called the classical solutions of problem (1)-(4) :

1. $f(t) \in C^\alpha[0, T]$;
2. $u(x, t) \in C^{2+\alpha, 1+\alpha/2}(D) \cap C^{1+\alpha, (1+\alpha)/2}(\bar{D})$;
3. the conditions (1)-(4) hold for these functions.

Lemma 1. Let conditions 1.1-1.5 be satisfied. If problem (1)-(4) has a classical solution $\{f(t), u(x, t)\}$ in the sense definition 1, then these functions are solution and takes (1), (2), (3) and

$$f(t) = h'(t) - u_x(c, t) + \psi_0(t), \quad t \in [0, T], \quad (5)$$

and the solution to problem (1), (2), (3), (5) is the solution to problem (1)-(4).

Proof. Let us assume that the pair of functions $\{f(t), u(x, t)\}$ is a solution to problem (1)-(4) in the sense of definition 1. If we integrate equations (1) in the interval $(0, c)$ with respect to the variable x we get:

$$\int_0^c u_t dx - \int_0^c u_{xx} dx = f(t) \int_0^c g(x) dx.$$

Taking into account the conditions of Lemma1, we obtain

$$h'(t) - u_x(a, t) + u_x(0, t) = f(t) \int_0^c g(x) dx, \quad t \in [0, T],$$

Here the reliability of formula (5) is obvious.

Now suppose that the pair of functions $\{f(t), u(x, t)\}$ is the classical solution of problem (1), (2), (3) and (5) we take into account formula.

Denoting $\theta(t) = \int_0^c u(x, t) dx - h(t)$, taking into account formula (5) and the conditions of Lemma 1, from the last inequality we obtain

$$\theta'(t) = 0, \quad \theta(0) = \int_0^c \varphi(x) dx - h(0) = 0.$$

It is clear that the only solution to the problem for the unknown $\theta(t) = 0$. From here $\int_0^c u(x, t) dx = h(t)$, $t \in [0, T]$ we get.

The lemma 1 is proved.

We construct a function $\tilde{\varphi}(x) \in C^{2+\alpha}[0, b]$, such that it satisfies $\tilde{\varphi}(x) \equiv \varphi(x)$, $x \in [0, a]$.

Under the conditions imposed on the input data, the function

$$F(x, t) = \tilde{\varphi}(x) + \frac{2\gamma(t)x - x^2}{2\gamma(t)} [\psi_0(t) - \psi_0(0)] + \frac{x^2}{2\gamma(t)} [\psi_1(t) - \psi_1(0)] \quad (6)$$

satisfies:

$$F(x, t) \in C^{2+\alpha, 1+\alpha/2}(\bar{D}), \quad F(x, 0) = \tilde{\varphi}(x), \quad F_x(0, t) = \psi_0(t), \quad F_x(\gamma(t), t) = \psi_1(t).$$

In relations (1)- (3), taking the substitution $u(x, t) = w(x, t) + F(x, t)$ we obtain:

$$\begin{aligned} w_t - w_{xx} &= \Phi(x, t), \quad (x, t) \in D, \\ w(x, 0) &= 0, \quad x \in [0, a], \\ w_x(0, t) &= w_x(\gamma(t), t) = 0, \quad t \in [0, T], \end{aligned} \quad (7)$$

where $\Phi(x, t) = f(t)g(x) + F_{xx}(x, t) - F_t(x, t)$.

We extend the function $\Phi(x, t)$ as follows

$$\tilde{\Phi}(x, t) = \begin{cases} \Phi(0, t), & -\infty < x < 0, \quad 0 \leq t \leq T, \\ \Phi(x, t), & 0 \leq x \leq \gamma(t), \quad 0 \leq t \leq T, \\ \Phi(\gamma(t), t), & \gamma(t) < x < +\infty, \quad 0 \leq t \leq T, \end{cases} \quad (8)$$

Then, the extend $\Phi(x, t)$ is bounded conditions and uniformly Holder continuous for each compact subset of D_T .

It can be shown that the potential

$$\begin{aligned} y(x, t) &= \int_0^t \int_{-\infty}^{+\infty} G(x - \xi, t - \tau) \tilde{\Phi}(\xi, \tau) d\xi d\tau = \\ &= \int_0^t \int_{-\infty}^{+\infty} G(x - \xi, t - \tau) \left[f(\tau)\tilde{g}(\xi) + \tilde{F}_{\xi\xi}(\xi, \tau) - \tilde{F}_\tau(\xi, \tau) \right] d\xi d\tau, \end{aligned} \quad (9)$$

(where the function $G(x, t) = \frac{1}{\sqrt{4\pi t}} \exp\left(-\frac{x^2}{4t}\right)$, $t > 0$ is the fundamental solution of equation $y_t - y_{xx} = 0$) has the following properties [2, chapter 19]:

2.1. $y(x, t) \in C^{2,1}\{(-\infty, +\infty) \times (0, T]\} \cap C^{1,0}\{(-\infty, +\infty) \times [0, T]\}$;

2.2 $y_t - y_{xx} = \tilde{\Phi}(x, t)$, $(x, t) \in (-\infty, +\infty) \times (0, T]$

2.3 $|y(x, t)| \leq m_1 \left\| \tilde{\Phi} \right\|_D^{(0)} \cdot t$, $(x, t) \in (-\infty, +\infty) \times [0, T]$;

2.4 $|y_x(x, t)| \leq m_2 \left\| \tilde{\Phi} \right\|_D^{(0)} \cdot t^{1/2}$, $(x, t) \in (-\infty, +\infty) \times [0, T]$.

Solution of the problem of determining $w(x, t)$ from relations (7) in the form

$$w(x, t) = z(x, t) + y(x, t)$$

where $y(x, t)$ is a function (9), $z(x, t)$ is the solution to the following problem

$$z_t - z_{xx} = 0, \quad (x, t) \in D,$$

$$z(x, 0) = 0, \quad x \in [0, a], \quad (10)$$

$$z_x(0, t) = -y_x(0, t), \quad v_x(\gamma(t), t) = -y_x(\gamma(t), t), \quad t \in [0, T].$$

The solution to problem (10) can be represented as [2, chapter 14]:

$$z(x, t) = -2 \int_0^t G(x, t - \tau) \rho_1(\tau) d\tau + 2 \int_0^t G(x - \gamma(\tau), t - \tau) \rho_2(\tau) d\tau, \quad (11)$$

where $\rho_1(t)$ and $\rho_2(t)$ are the solution of the systems of integral equations

$$-y_x(0, t) = \rho_1(t) + 2 \int_0^t G_x(-\gamma(\tau), t - \tau) \rho_2(\tau) d\tau, \quad (12)$$

$$-y_x(\gamma(t), t) = \rho_2(t) - 2 \int_0^t G_x(\gamma(t) - \gamma(\tau), t - \tau) \rho_1(\tau) d\tau.$$

Note that under the accepted conditions for the initial data $\rho_i(t) \in C[0, T]$, $i = 1, 2$. Given the above, you can write

$$u(x, t) = F(x, t) + y(x, t) - 2 \int_0^t G(x, t - \tau) \rho_1(\tau) d\tau + 2 \int_0^t G(x - \gamma(\tau), t - \tau) \rho_2(\tau) d\tau, \quad (13)$$

Thus, the inverse problem of determining $\{f(t), u(x, t)\}$ from (1)-(3),(5) is reduced

To a system of integral equations (13),(5).

Definition 2. $\{f(t), u(x, t)\}$ functions called a generalized solution of the inverse problem (1)-(4) if:

1) $f(t) \in C[0, T]$;

2) $u(x, t) \in C^{1,0}(\bar{D})$;

3) these functions satisfy the system of integral equations (13),(5).

Theorem 1. Let the initial data of problem (1)-(4) satisfy conditions 1.1-1.5 .

Then there exists a $T_1 \in (0, T]$ such that in the region $\overline{D}_1 = [0, \gamma(t)] \times [0, T_1]$ the inverse problem has a solution in the sense of the definition 2.

Proof. First we show that for each given $f(t) \in C([0, T])$ the function $u(x, t)$ found from (13) belongs to $C^{1,0}(\overline{D})$.

Indeed, under the conditions of Theorem 1, the function $u(x, t)$ from (13) and the function $u_x(x, t)$ from

$$\begin{aligned} u_x(x, t) &= F_x(x, t) + y_x(x, t) - 2 \int_0^t G_x(x, t - \tau) \rho_1(\tau) d\tau + \\ &+ 2 \int_0^t G_x(x - \gamma(\tau), t - \tau) \rho_2(\tau) d\tau. \end{aligned} \quad (14)$$

are continuous is a \overline{D} for each given $f(t) \in C([0, T])$.

Now let us show the existence of the function $f(t) \in C([0, T])$. Denote $Q = C([0, T])$. Equation (5) will be written in operator form:

$$\begin{aligned} M[f(t)] &= f(t), \quad M : Q \rightarrow Q \\ M[f(t)] &= h'(t) + \psi_0(t) - F_x(c, t) - \\ &- \int_0^t \int_{-\infty}^{+\infty} G_x(c - \xi, t - \tau) [f(\tau) \tilde{g}(\xi) + F_{\xi\xi}(\xi, \tau) - F_\tau(\xi, \tau)] d\xi d\tau - \\ &- 2 \int_0^t G_x(c, t - \tau) \rho_1(\tau) d\tau + 2 \int_0^t G_x(c - \gamma(\tau), t - \tau) \rho_2(\tau) d\tau. \end{aligned} \quad (15)$$

Let $Q' = \{f | f(t) \in C[0, T], |f(t)| \leq f_0, t \in [0, T], \text{ where } f_0 \text{ is a constant number}\}$ It is clear that $M[Q'] \subset Q$.

We show the uniform boundedness and equicontinuity of the set $M[Q']$.

First, we note inequalities that will be useful to us later [1,2].

$$G(x, t - \tau), G(x - \gamma(\tau), t - \tau) \leq m_3(t - \tau)^{-1/2}, \quad (16)$$

$$|G_x(c, t - \tau)|, |G_x(c - \gamma(\tau), t - \tau)| \leq m_4(t - \tau)^{-1/2}, \quad (17)$$

$$\begin{aligned} &|G_x(x - \gamma(t), t_1 - \tau) - G_x(x - \gamma(t), t_2 - \tau)| \leq \\ &m_5(t_1 - t_2)^{(1+\alpha)/2} (t_2 - \tau)^{-3/2} \exp\left(-\frac{(x - \xi)^2}{4(t_2 - \tau)}\right), \end{aligned} \quad (18)$$

From properties 2.3 and 2.4 for the functions $y(x, t)$ and $y_x(x, t)$ we have:

$$|y(x, t)| \leq m_1 \left\| \tilde{\Phi} \right\|_D^{(0)} t \leq m_1 \left[f_0 + \|F\|_D^{(2,1)} \right] t, \quad (x, t) \in (-\infty, +\infty) \times [0, T], \quad (19)$$

$$|y_x(x, t)| \leq m_2 \left\| \tilde{\Phi} \right\|_D^{(0)} t^{1/2} \leq m_2 \left[f_0 + \|F\|_D^{(2,1)} \right] t, \quad (x, t) \in (-\infty, +\infty) \times [0, T], \quad (20)$$

Taking into account inequalities (16) and (20), from (12) we have

$$|\rho_1(t)| \leq m_6 \left[f_0 + \|F\|_D^{(2,1)} \right] T^{1/2} + m_7 \|\rho_2\|_T^{(0)} T^{1/2}$$

$$|\rho_2(t)| \leq m_8 \left[f_0 + \|F\|_D^{(2,1)} \right] T^{1/2} + m_9 \|\rho_1\|_T^{(0)} T^{1/2}$$

The last inequalities are true for every $t \in [0, T]$. Hence, they must also hold for the maximum values of the left-hand sides

$$\|\rho_1\|_T^{(0)} \leq m_6 \left[f_0 + \|F\|_D^{(2,1)} \right] T^{1/2} + m_7 \|\rho_2\|_T^{(0)} T^{1/2}$$

$$\|\rho_2\|_T^{(0)} \leq m_8 \left[f_0 + \|F\|_D^{(2,1)} \right] T^{1/2} + m_9 \|\rho_1\|_T^{(0)} T^{1/2}.$$

Summing up the last inequalities we obtain

$$\|\rho_1\|_T^{(0)} + \|\rho_2\|_T^{(0)} \leq m_{10} \left[f_0 + \|F\|_D^{(2,1)} \right] T^{1/2} + m_{11} \left[\|\rho_1\|_T^{(0)} + \|\rho_2\|_T^{(0)} \right] T^{1/2}.$$

Let say $T_1 \in (0, T]$ is a number such that $m_{11}T_1^{1/2} < 1$.

Then from the last inequality we have

$$\|\rho_1\|_T^{(0)} + \|\rho_2\|_T^{(0)} \leq m_{12} \left[f_0 + \|F\|_D^{(2,1)} \right] T_1^{1/2}, \quad (21)$$

Taking in (14) $x = c$ and taking into account the inequalities (17),(20),(21) we get

$$|u_x(c, t)| \leq m_{13} \left[f_0 + \|F\|_D^{(2,1)} \right] T_1^{1/2}. \quad (22)$$

Thus, for any $f(t) \in Q'$

$$M[f(t)] = |h'(t)| + |\psi_0(t)| + m_{13} \left[f_0 + \|F\|_D^{(2,1)} \right] T_1^{1/2},$$

that, is the set $M[Q']$ is uniformly bounded.

Now we will show the equcontinuity of the set $M[Q']$: we write the formula (15) for different values of $t_1, t_2 \in (0, T)$ ($t_1 > t_2$ for clarity) and estimate their difference

$$\begin{aligned} |M[f(t_1)] - M[f(t_2)]| &\leq |h'(t_1) - h'(t_2)| + |\psi_0(t_1) - \psi_0(t_2)| + |u_x(c, t) - u_x(c, t_2)| \leq \\ &\leq |h'(t_1) - h'(t_2)| + |\psi_0(t_1) - \psi_0(t_2)| + |F_x(c, t_1) - F_x(c, t_2)| + \\ &+ |y_x(c, t_1) - y_x(c, t_2)| + 2 \int_0^{t_2} |G_x(c, t_1 - \tau) - G_x(c, t_2 - \tau)| |\rho_1(\tau)| d\tau + \\ &+ 2 \int_{t_2}^{t_1} |G_x(c, t_1 - \tau)| \cdot |\rho_1(\tau)| d\tau + 2 \int_0^{t_2} |G_x(c - \gamma(\tau), t - \tau) - \\ &- G_x(c - \gamma(\tau), t_2 - \tau)| |\rho_2(\tau)| d\tau + 2 \int_{t_2}^{t_1} |G_x(c - \gamma(\tau), t - \tau)| \cdot |\rho_2(\tau)| d\tau. \end{aligned}$$

Taking into account conditions 1.3 and 1.4 of theorem 1, the properties of functions (6) and (9), we can write

$$\begin{aligned} |h'(t_1) - h'(t_2)| &\leq m_{14}(t_1 - t_2), \\ |\psi_0(t_1) - \psi_0(t_2)| &\leq m_{15}(t_1 - t_2), \\ |F_x(c, t_1) - F_x(c, t_2)| &\leq m_{16}(t_1 - t_2), \\ |y_x(c, t_1) - y_x(c, t_2)| &\leq m_{17}(t_1 - t_2). \end{aligned}$$

Using inequalities (14) and (18) we obtain

$$\begin{aligned} &\int_{t_2}^{t_1} |G_x(c, t - \tau)| \cdot |\rho_1(\tau)| d\tau \leq m_{18} \|\rho_1\|_T^{(0)} (t_1 - t_2)^{1/2}, \\ &\int_{t_2}^{t_1} |G_x(c - \gamma(\tau), t - \tau)| \cdot |\rho_2(\tau)| d\tau \leq m_{19} \|\rho_2\|_T^{(0)} (t_1 - t_2)^{1/2}, \\ &\int_0^{t_1} |G_x(c, t_1 - \tau) - G_x(c, t_2 - \tau)| \cdot |\rho_1(\tau)| d\tau \leq \\ &\leq m_{20} \|\rho_1\|_T^{(0)} (t_1 - t_2)^{(1+\alpha)/2} \int_0^{t_2} (t_2 - \tau)^{-3/2} \exp(-c^2/4(t_2 - \tau)) d\tau \\ &\int_0^{t_2} |G_x(c - \gamma(\tau)t_1 - \tau) - G_x(c - \gamma(\tau)t_2 - \tau)| \cdot |\rho_2(\tau)| d\tau \leq \\ &\leq m_{21} \|\rho_2\|_T^{(0)} (t_1 - t_2)^{(1+\alpha)/2} \int_0^{t_2} (t_2 - \tau)^{-3/2} \exp(-(c - \gamma(\tau))^2/(4(t_2 - \tau))) d\tau. \end{aligned}$$

Generalizing the above estimates, we conclude that $M[Q']$ is an equicontentious set.

Thus, by Arzela-Ascoli theorem, the set $M[Q']$ is compact in Q [7]. In this case, according to the Schauder theorem, the operator $M[f(t)]$ has at least one fixed point, in other words, the operator equation $M[f(t)] = f(t)$ has solution $f(t) \in Q = C(0, T)$.

Theorem 1 is proved.

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